Optimization strategies for hardware-based cofactorization

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- 1. Optimize the COPACOBANA without changing the design.
- 2. After you have suceeded, analyze upcoming primitives like Edwards curves.

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Known factoring algorithms

- Best known factorization algorithm for large numbers (above 300 bits, say) is the General Number Field Sieve (GNFS).
- In the so called Cofactorization Step a large number of smaller integers have to be factored.
- For these factorizations LENSTRA's Elliptic Curve Method (ECM) is used.

Fact:

Many runs of the same algorithm can be efficiently realized on a dedicated hardware cluster.

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Boards FPGAs ECM modules









BoardsFPGAsECM modulesSmall modules \implies more parallelism, less inputs



BoardsFPGAsECM modulesLarge modules \implies less parallelism, more inputs



Boards FPGAs ECM modules Mixed modules not allowed!



Optimize!



We want:

- A generic model of the cluster.
- ► A fast algorithm that computes the optimal distribution.
- A way of measuring the runtime achievement...
- ... against what?!?

Specifically in the case of the GNFS we need:

- Estimates on the number of parallel units per FPGA.
- Estimates on the average cost of one run of the ECM.
- A mathematical model of the ouputs of the GNFS: Difficult!

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Optimize over all configurations and classes, using e.g. BELLMAN's dynamic programming and a greedy heuristic!

Assume we are constructing modules for 17i-bit integers, given six data sets $\mathcal{D}_1, \ldots, \mathcal{D}_6$.

Number of parallel processes per chip:

Bitlength $17i$	51	68	85	102	119	136	153
Processes n_i	22	18	15	12	10	9	8

Average runtime of an ECM on the FPGA (in μ s):

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Input distribution for dataset \mathcal{D}_1 :



Distribution on the classes:



Optimal classes:



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Runtime gain

- Let $K \cdot g$ be the maximal size of the inputs.
- We compare the runtime to an unoptimized cluster.
- ► On such a cluster there are only modules for K · g bit numbers.
- The runtime is between

$$\sigma_{\mathcal{D}}^{-}(N,K) := \frac{1}{N} \sum_{i=1}^{K} \frac{c_i a_i}{n_K} \text{ and } \sigma_{\mathcal{D}}^{+}(N,K) := \frac{\#\mathcal{D}c_K}{Nn_K}.$$

Let γ_D[±] denote the runtime gain of τ_D against σ_D[±] in percent.
We obtain:

	\mathcal{D}_1	\mathcal{D}_2	\mathcal{D}_3	\mathcal{D}_4	\mathcal{D}_5	\mathcal{D}_6
$\gamma_{\mathcal{D}}^{-}$	17.47	16.97	17.66	18.38	18.4	16.88
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Optimizing several clusters

We can use our model to optimize m clusters in parallel, obtaining:



	\mathcal{D}_1	\mathcal{D}_2	\mathcal{D}_3	\mathcal{D}_4	\mathcal{D}_5	\mathcal{D}_6
$\lim_{N\to\infty}\gamma_{\mathcal{D}}^{-}$	20.81	20.58	20.70	20.56	20.00	19.81
$\lim_{N\to\infty}\gamma_{\mathcal{D}}^{+}$	35.99	35.66	35.82	35.63	34.80	34.51

Online reconfiguration

- We have seen that the result of the optimization depends heavily on the input.
- On many clusters it is possible to reconfigure the FPGAs during the runtime of the cofactorization step.
- If we could use such a method, we could run a daemon on the controlling host computer that keeps track of the statistics of the inputs.
- The daemon has also to estimate when a reconfiguration makes sense.
- Further speedup possible!

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 - Estimates on the number of parallel units per FPGA.
 - Estimates on the average cost of one run of the ECM.
 - But: No mathematical model of the ouputs of the GNFS!

Thus regardless of the coordinate choices we can optimize the cofactorization step in hardware considerably.

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Edwards introduced in 2007 a new normal form for elliptic curves. First Question

Do we have a speedup for addition and multiplication?

Second Question

Can these curves be used on the COPACOBANA?

- Let K be a field of characteristic $p \neq 2$.
- ► Then many elliptic curves C are birationally equivalent to a curve of the form

$$x^2 + y^2 = 1 + dx^2 y^2$$

where $d \notin \{0, 1\}$.

- If C is not equivalent to a curve in Edwards form, then its quadratic twist is.
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Transforming to Edwards form



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Addition on Edwards curves

We can define the following unified addition law:

$$(x_1, y_1) + (x_2, y_2) = \left(\frac{x_1y_2 + y_1x_2}{1 + dx_1x_2y_1y_2}, \frac{y_1y_2 - x_1x_2}{1 - dx_1x_2y_1y_2}\right).$$

- ► Addition is well-defined if *d* is a nonsquare in the groundfield.
- ▶ The point (0,1) is the neutral element with respect to this addition law.
- Inverse of a point (x, y) is given by

$$-(x,y) = (-x,y).$$













Twisted Edwards curves

- ▶ In 2008, Bernstein et al. introduced twisted Edwards curves.
- Prevents that we have to enlarge the ground field.
- ► A twisted Edwards curve $E_{a,d}$ of the curve E is given by the equation

$$ax^2 + y^2 = 1 + dx^2y^2.$$

- Here $a \neq d$ are both nonzero.
- ► Note that for parameters a₁, a₂, d₁, d₂ the curves E_{a1,d1} and E_{a2,d2} are quadratic twists of each other if a₁d₂ = a₂d₁.
- ► If further a₁/a₂ a square in K, then the curves are isomorphic, e.g. using the map

$$(x,y) \mapsto (\sqrt{a_1/a_2} \cdot x, y)$$

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Available coordinate choices

- Bernstein and Lange introduced different types of Edwards coordinates.
- Clearly this choice is crucial for the speed of the basic operations on the curve.
- We need to analyze the different types of coordinates to each other.
- Also we have to compare these to well-known coordinates (for classical elliptic curves).
- ► As usual: Count cost in terms of basic operations.

Operation in the ground field	Cost
Multiplication	M
Squaring	S
Multiplication with a constant	D
Addition	Α

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Projective Edwards coordinates

- ► Affine point on an Edwards curve E is given by a tuple (x₁, y₁).
- Projectively the curve has the homogenized form

$$X^2 Z^2 + Y^2 Z^2 = Z^4 + dX^2 Y^2$$

► Here the projective point (X: Y: Z) with Z ≠ 0 corresponds to the affine point (X/Z, Y/Z).

Cost

General addition: $10\mathbf{M} + 1\mathbf{S} + 1\mathbf{D} + 7\mathbf{A}$. Doubling: $3\mathbf{M} + 4\mathbf{S} + 6\mathbf{A}$.

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General addition: 10M + 1S + 1D + 7A. Doubling: 3M + 4S + 6A. For Inverted Edwards Coordinates a projective point $(X\colon Y\colon Z)$ corresponds to the affine point (Z/X,Y/X).

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General addition: $9\mathbf{M} + 1\mathbf{S} + 1\mathbf{D} + 7\mathbf{A}$. Doubling: $3\mathbf{M} + 4\mathbf{S} + 1\mathbf{D} + 6\mathbf{A}$.

Speedup of one multiplication for general addition, but one more multiplication with a constant for doubling!

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Montgomery coordinates

- On a Mongomery curve By² = x³ + Ax² + x a point (x, y) is represented by a pair (X: Z) such that X/Z = x.
- This representation does not distinguish (x, y) from (x, -y)!
- Thus P + Q can only be computed if one knows

$$P, Q$$
 and $P - Q$.

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Comparison to Edwards coordinates

- Montgomery curves have a faster differential point addition.
- Differential addition chains in general longer than standard ones.
- When using projective Edwards coordinates on twisted Edwards curves: Speedup possible.

Example

Scalar multiplication [s]P with 256 bit scalar s: **Montgomery coordinates:** On avg. $6\mathbf{M} + 4\mathbf{S} + 1\mathbf{D}$ per bit. **Edwards coordinates:** On avg. $4.86\mathbf{M} + 4.12\mathbf{S} + 0.194\mathbf{D}$ per bit. Speedup of $1.14\mathbf{M} - 0.12\mathbf{S} + 0.803\mathbf{D}$.

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Use of Edwards coordinates for the COPACOBANA

- During the GNFS we will factor most of the time smallish numbers.
- For such numbers the Edwards form does not yet yield any speedup.
- Additionally: High development cost if one wants to redesign the ECM modules!
- Thus it seems that for the ECM on the COPACOBANA the use of Edwards coordinates does not (yet) make sense.

Problem

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Ideas:

- ▶ Exploiting the additional symmetry of Edwards curve, i.e. the operation $(x, y) \rightarrow (x, -y)$.
- Can we use existing constructions for Weierstraß curves in the case of Edwards curves?
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- Independent of the concrete coordinate choices.
- ► Already here a speedup of up to 30%.

Optimizations of the ECM modules:

- Using optimized coordinates.
- Problem: High development cost!

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The end.

